Submarine simulator

A **submarine simulator** is usually a <u>computer game</u> in which the player commands a <u>submarine</u>. The usual form of the game is to go on a series of missions, each of which features a number of encounters where the goal is to sink <u>surface ships</u> and to survive counterattacks by <u>destroyers</u>. Submarine simulators are notable for the highly-variable pace of the game; it may take hours of simulated time to get into position to attack a well-defended <u>convoy</u>, and sub simulators typically include an option for players to adjust the ratio of real time to simulated time up and down as desired.



A submarine in Second Life

Most submarine simulators use World War II as the setting; its submarine warfare was lengthy and intense, the historical material is extensive, and the limited capabilities of

the period's submarines place a high premium on game playing skill. Games usually feature either US submarines in the Pacific Ocean, or German <u>U-boats</u> in the Atlantic Ocean. Another popular category is modern <u>attack submarines</u>, especially those of the <u>Los Angeles class</u> also known as "688s" after the hull identification number of the first vessel of the class.

Game displays generally include an overhead map or "radar" view, showing the submarine and any ships whose position can be detected, the <u>periscope</u> view if the sub is close enough to the surface, a set of gauges showing depth and course, and a boat plan showing <u>torpedo</u> availability, damage to various subsystems and other in-game issues that may arise.

The first submarine simulator available to the civilian public was Thorn EMI's *Submarine Commander* of 1982.

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Titles

Name	Year
1914 Shells of Fury	2007
688 Attack Sub	1988
688(I) Hunter/Killer	1997
Aces of the Deep	1994
<u>AquaNox</u> series. (Heavily stylized, futuristic series sharing more in common with space combat simulators.)	1996-2020
Archimedean Dynasty (First game of AquaNox series)	1996
Barotrauma	2019-
Captain Sonar	2016
Cold Waters	2017
Command: Aces of the Deep	1995
Crush Depth: U-Boat Simulator	2021
Dangerous Waters	2005
Danger from the Deep (Open source)	2003
Das Boot: German U-Boat Simulation	1990-91
Deadly Tide	1996
Depthcharge	1977
Deep Fighter: The Tsunami Offensive	2000
Dive to the Titanic	2010
Enigma: Rising Tide	2003/2005
Fast Attack: High Tech Submarine Warfare	1996
GATO	1984
Grey Wolf: Hunter of the North Atlantic	1994

Harpoon	1989
The Hunt for Red October	1987-90
Iron Wolves	1996
Iron Wolf VR (virtual reality game, early access)	2017
OpenSSN (Open source)	2010
Operation Neptune	1991
Periscope	1966
Radar Mission (Mode B)	1990
Red Storm Rising	1988
Silent Depth Submarine Simulation	2016, 2018
Silent Service series	1985, 1990
Silent Hunter	1996
Silent Hunter II	2001
Silent Hunter III	2005
Silent Hunter 4: Wolves of the Pacific	2007
Silent Hunter 5: Battle of the Atlantic	2010
Silent Steel	1995
SSN-21 Seawolf	1994
Steel Diver	2011
Submarine Commander	1982
Sub Battle Simulator	1987-88
Sub Command	2001
Sub Culture	1997
Sub Hunt	1982
Sub Hunter	1977
Sub Mission	1986
Subwar 2050	1994
Tom Clancy's SSN	1996
UBOAT	2019
U-Boat Simulator (Android)	2013
Up Periscope!	1986
Virtual Sailor	1999
Wolfpack	1990
Wolfpack	2019

The adventure game <u>Codename: ICEMAN</u> (1989) by <u>Sierra On-line</u> contained a submarine simulator portion.

The vehicle simulator game <u>Naval Ops: Warship Gunner 2</u> (2006) by <u>Koei</u> features submarine hulls & puts the player through several submarine piloting missions, though several other missions are also restricted against submarine use.

AUV Simulators

There are also a number of simulators available for underwater robots such as <u>AUVs</u>. These simulators are commonly used by research institutes for testing robot control and coordination algorithms before or during the development of a submarine. One of them is UWSim, the Underwater Simulator, which was developed in the IRSLab for marine robotics research and development. UWSim started with the RAUVI and TRIDENT research projects as a tool for testing and integrating perception and control algorithms before running them on the real robots and has continued its development until today.^[1]

References

 Prats, Mario; Perez, Javier; Fernandez, J. Javier; Sanz, Pedro J. (2012). "An open source tool for simulation and supervision of underwater intervention missions". 2012 IEEE/RSJ International Conference on Intelligent Robots and Systems. pp. 2577–2582. doi:10.1109/IROS.2012.6385788 (https://doi.org/10.1109%2FIROS.2012.6385788). ISBN 978-1-4673-1736-8.

External links

- Subsim.com, a comprehensive information and review site (http://www.subsim.com)
- IRSLab (http://www.irs.uji.es/)
- UWSim (http://www.irs.uji.es/uwsim/)

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